

# Unfolding recurrence by Green's functions for optimized reservoir computing

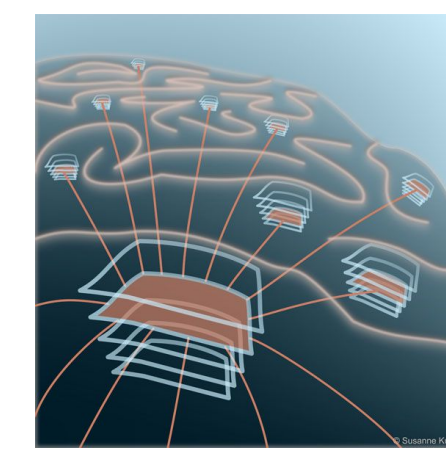
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Published in: Advances in Neural Information Processing Systems 33 (2020), Advances in Continuous and Discrete Models 2022.1 (2022)



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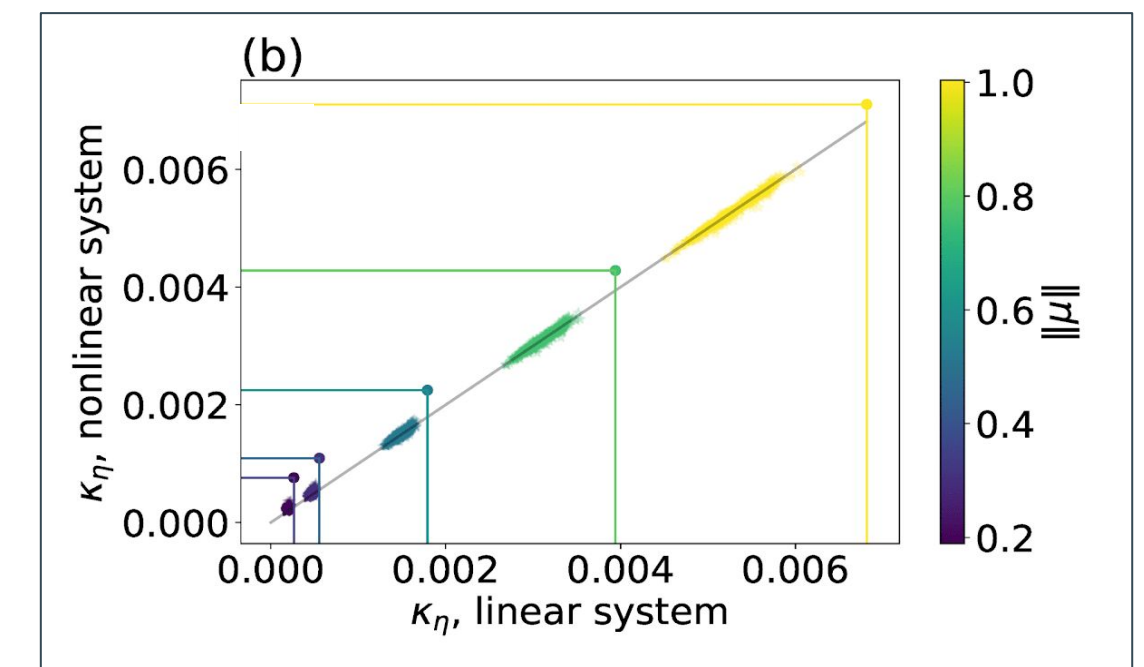
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## Setup

- Reservoir Computing as computationally efficient machine learning system<sup>1,2</sup>
- Task: Binary classification of one-dimensional, time-dependent stimuli
- Dependence of the performance on reservoir properties has already been studied<sup>3,4</sup>

## Non-linear vs. linear system

- Clear benefit compared to random  $u$
- Gain from non-linearity varies with linear separability of stimuli
- Significant performance increase for low linear separabilities



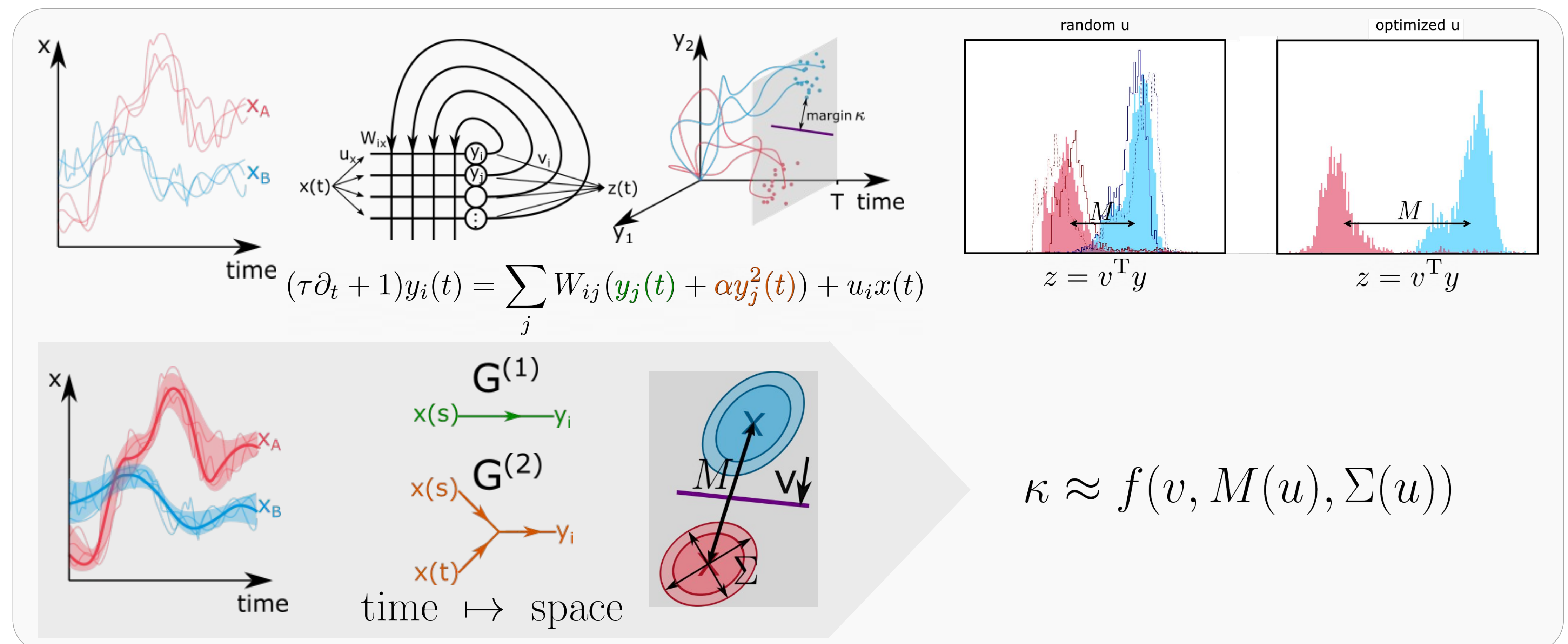
## The soft margin

- Joint optimization of input and readout projections
- Classification quality measure: margin  

$$\kappa(u, v) = \min_{\nu} (\zeta_{\nu} v^T y^{u, \nu})$$
- Differentiable and less sensitive to exact realizations of stimuli: soft margin  

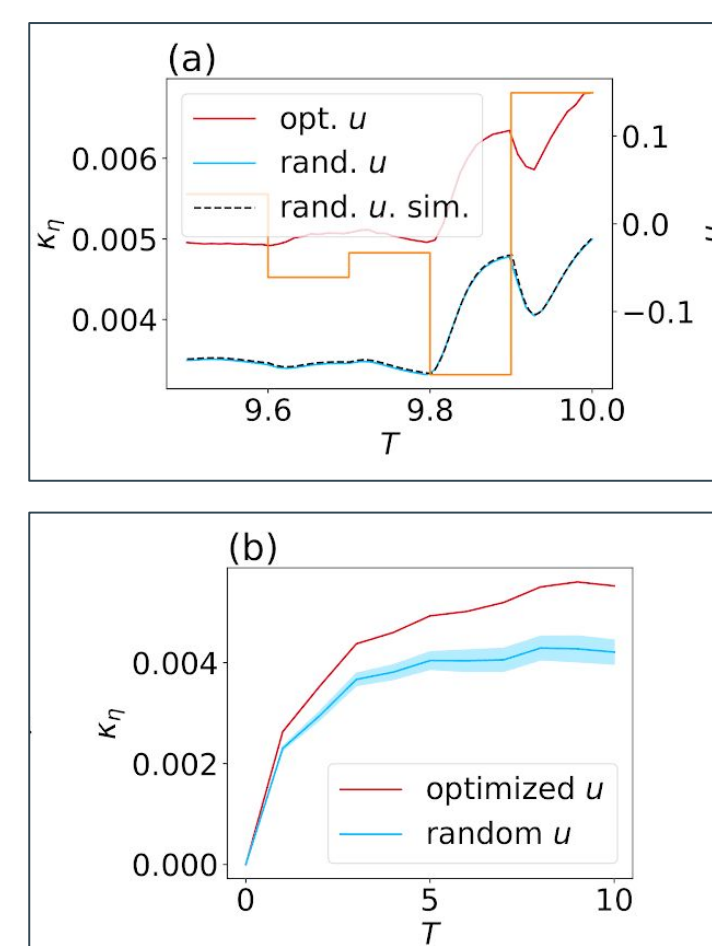
$$\kappa_{\eta}(u, v) = -\frac{1}{\eta} \ln \left[ \sum_{\nu} \exp(-\eta \zeta_{\nu} v^T y^{u, \nu}) \right]$$
- For large set of sample data:  $\kappa_{\eta}$  becomes cumulant generating function  

$$\kappa_{\eta}(u, v) \approx v^T M^u - \frac{1}{2} \eta v^T \Sigma^u v$$



## Dynamics and optimization

- Non-linear dynamics can be approximated as perturbation series for small  $\alpha$
- $M$  becomes sensitive to second order stimulus statistics,  $\Sigma$  becomes sensitive to fourth order
- For fixed reservoir, stimulus and readout time: considerable increase in classification performance



## Conclusion

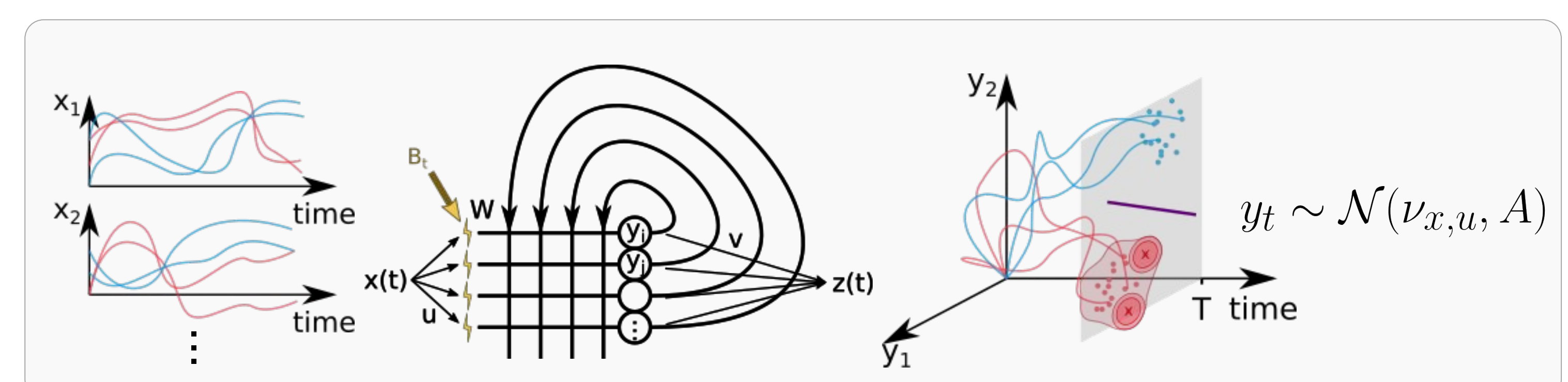
- Unfold recurrent dynamics via Green's functions
- Soft margin yields closed-form expressions for optimization
- Trade-off between separation and variability in readout direction
- Significant gain from non-linearity for weakly linear separable data
- Clear absolute performance gain also in linearly well separable ECG5000 dataset

## Classification by stochastic linear RNN

- Introduce noise to the dynamics to leverage sensitivity on exact realizations
- Minimize empirical risk of misclassification based on probability density

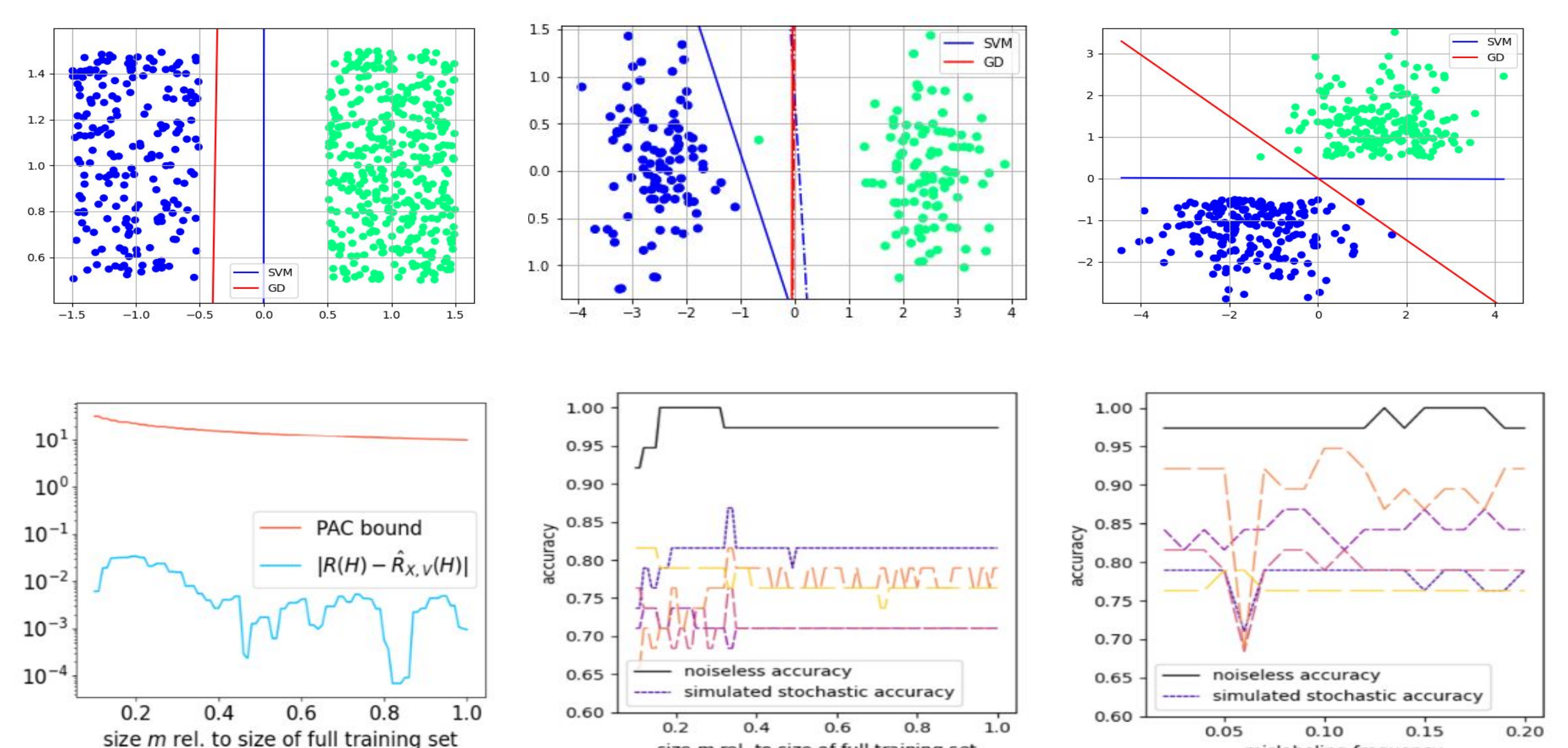
$$\min_{u, \omega, b} \hat{R}_{(x, v)}(H) = \min_{u, \omega, b} \frac{1}{m} \sum_{i=1}^m \mathbb{P}_B(H(x_i) \neq v_i) = \min_{u, \omega, b} \frac{1}{m} \sum_{i=1}^m \Phi \left( -v_i \cdot \frac{\langle \nu_{x_i, u}, \omega \rangle + b}{\sqrt{\omega^T A \omega}} \right)$$

$$\mathbb{P}(\text{sign}(\langle y_t, \omega \rangle + b) \neq v)$$



## Optimization strategy

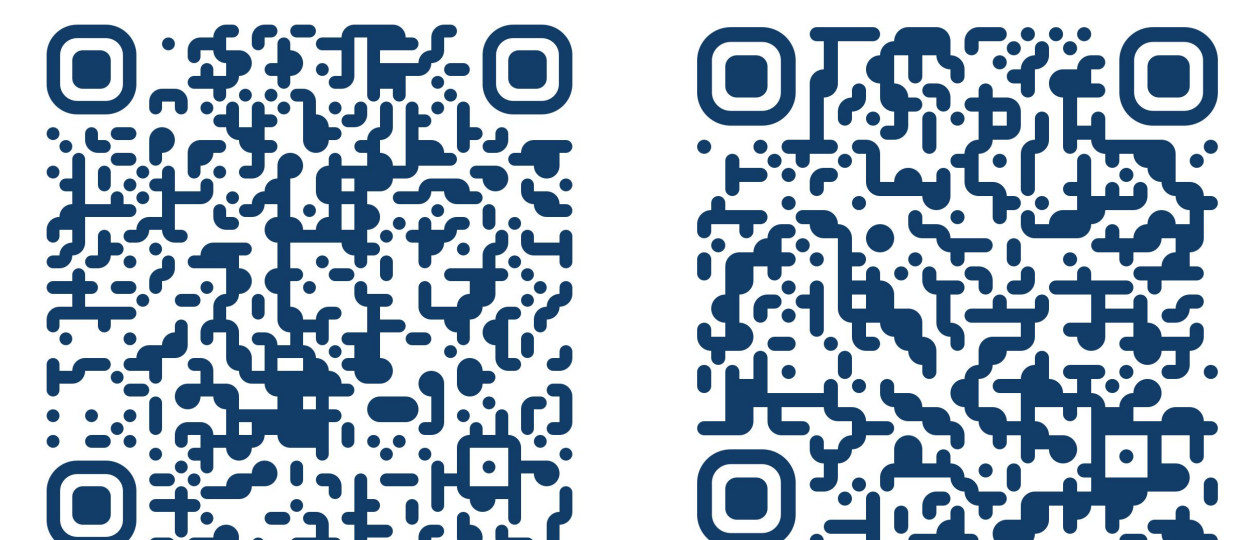
- Use Rademacher complexity to guarantee empirical risk convergence
- Contrast empirical risk for noisy and noise-free dynamics
- The optimal classifier is robust to outliers and perturbations



## References

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Links to the papers:



Analytically unfolding recurrent dynamics into Green's functions is a versatile approach that may be used as a general purpose scheme to analyze recurrent networks.